



Alpha3D

Mobile mapping solution

Solution Description

Alpha3D

Dominant performance to make your work more mobile

CHC Navigation offers to geospatial professionals our premium high-performance, vehicle-independent mobile mapping solution to capture mass data in continuously changing world environments on dynamics, enabling them to get work done quickly and more accurately to increase their ROI.

The Alpha3D combines state-of-the-art high-performance hardware, such as long range, ultra-high speed, precise laser scanner, high-resolution HDR panoramic camera in combination with advanced GNSS receiver and high precision IMU, in one instrument with light weight and compact but in same time rugged design. All these features keep Alpha3D as one of most innovative system in market today.

Applications



Roads & Highways



Rail & Infrastructure



Tunnels



Digital city



Infrastructure utilities



Mining



Water



Airports



Public safety

Key Features











High performance laser scanner

- Long range scanning up to 420m
- Extremely high-speed scanning of 1M points per second
- · High point cloud density even on high speed driving
- High quality of point cloud with low range noise

High resolution 360° image

- 30 MP HDR panoramic camera with superb image quality
- Fully calibrated point clouds and panorama images
- You can add additional imagery sensors to get extra information for application needs

Ready now, thinking about future

- Two RS232 ports for external device connection
- Ready to add 2nd scanner for more density of point cloud
- 2nd GNSS antenna to work on railway or water applications
- Easy-In easy-out SSD hard disc for raster data transfer

Capture and control data easily with CoCapture

- Manage the mission and automatically capture data
- BYOD, device free, any browser based operation
- WiFi or LAN cable connection
- Very simple and intuitive, user-friendly design

CoProcess software to manage scanning projects

- Intuitive user interface with rich functionality
- Semi-automated feature extractions
- Powerful engine can support massive data processing
- Easily export extracted information into CAD or GIS deliverables with our SW plugins



Vehicle-independent platform

Whatever the task is, the Alpha3D is easily mounted on a variety of platforms, including different type of vehicles, trains, railway trolleys and boats, rapidly and efficiently collects the high density, accurate point clouds and powerful images data but also adds extra information from additional sensors, such as high-resolution camera, thermal camera, GPR, echo sounder or extra profiler.



Get new revenue and increase ROI

Whatever the task is, the Alpha3D is easily mounted on a variety of platforms, including different type of vehicles, trains, railway trolleys and boats, rapidly and efficiently collects the high density, accurate point clouds and powerful images data but also adds extra information from additional sensors, such as high-resolution camera, thermal camera, GPR, echo sounder or extra profiler.

Specifications

roof rack extension

General sy	stem pe	rforma	nce	
Number of laser		anner head		
scanners	future possible to add 2nd scanner			
	head on a	additional	platform	
Typical horizontal accuracy	< 0.030 m		p	
Typical vertical accuracy	< 0.025 m			
Accuracy conditions		control poi	into	
Accuracy conditions		· ·		
Control unit		conditions	industrial P	<u></u>
Control unit				C,
Et al. L. Granner		r consump		
Field software	· ·		r-based, no	0
0		on required		
Control interface		-	r laptop), V	VIFI
		able conne		
Data storage			D hard disl	<
		3 interface		
3rd party hardware	,		port for 2n	d
synchronization	GNSS an	tenna2 x R	S232	
			ts (NMEA :	
Mounting	Vehicle in	ndepender	nt solution,	
	suits for r	oad, rail a	nd	
	water-bas	sed applic	ation	
Laser scanner				
Laser class	1 (in acco	rdance wit	:h IEC 6082	5-1:2014
Measuring principle	Time of flight measurement, echo signal digitization, online			
	waveform	processir	ng	
Effective measurement rate(1)	300 kHz	500 kHz	750 kHz	1 MHz
Maximum range, target	420 m	330 m	270 m	235 m
reflectivity > 80% ⁽²⁾				
NA 1				
Maximum range, target	150 m	120 m	100 m	85 m
	150 m	120 m	100 m	85 m
reflectivity > 10% ⁽²⁾	150 m	120 m	100 m	85 m
		120 m	100 m	85 m
reflectivity > 10% ⁽²⁾ Minimum range	1.2 m	120 m	100 m	85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾	1.2 m 5 mm		100 m	85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾ Precision ⁽⁴⁾	1.2 m 5 mm 2 mm 360° "full	circle"		85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate	1.2 m 5 mm 2 mm 360° "full Up to 1 0	circle" 00 000 poi	nts/sec	85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate Scan speed (selectable)	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250	circle" 00 000 poi) scans/sec	nts/sec	85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate Scan speed (selectable)	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250	circle" 00 000 poi) scans/sec	nts/sec	85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate Scan speed (selectable) Dimensions of	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31	circle" 00 000 poi) scans/sec × 67.2 cm	nts/sec	85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate Scan speed (selectable) Dimensions of instrument	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" ×	circle" 00 000 poi) scans/sec	nts/sec	85 m
reflectivity > 10%(2) Minimum range Accuracy(3) Precision(4) Field of view Scan rate Scan speed (selectable) Dimensions of instrument Weight of instrument	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg	circle" 00 000 poi) scans/sec × 67.2 cm 12.2" × 26	nts/sec	85 m
reflectivity > 10% ⁽²⁾ Minimum range Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate Scan speed (selectable) Dimensions of instrument	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49	circle" 00 000 poi) scans/sec × 67.2 cm	nts/sec	85 m
reflectivity > 10%(2) Minimum range Accuracy(3) Precision(4) Field of view Scan rate Scan speed (selectable) Dimensions of instrument Weight of instrument	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49 24.4" × 1	circle" 00 000 poi 0 scans/sec × 67.2 cm 12.2" × 26 .7 × 35.3 c 9.29" × 13	nts/sec	
reflectivity > 10%(2) Minimum range Accuracy(3) Precision(4) Field of view Scan rate Scan speed (selectable) Dimensions of instrument Weight of instrument Dimensions of battery Weight of battery	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49 24.4" × 1	circle" 00 000 poi 0 scans/sec × 67.2 cm 12.2" × 26 .7 × 35.3 c 9.29" × 13 kg (depen	nts/sec	
reflectivity > 10%(2) Minimum range Accuracy(3) Precision(4) Field of view Scan rate Scan speed (selectable) Dimensions of instrument Weight of instrument Dimensions of battery	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49 24.4" × 1 Up to 52 72 × 31 ×	circle" 00 000 poi 0 scans/sec × 67.2 cm 12.2" × 26 .7 × 35.3 c 9.29" × 13 kg (depen	nts/sec .37" .78" ding on ce	
reflectivity > 10%(2) Minimum range Accuracy(3) Precision(4) Field of view Scan rate Scan speed (selectable) Dimensions of instrument Weight of instrument Dimensions of battery Weight of battery Dimensions of optional	1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49 24.4" × 1 Up to 52 72 × 31 ×	circle" 00 000 poi 0 scans/sec × 67.2 cm 12.2" × 26 .7 × 35.3 c 9.29" × 13 kg (depen 12 cm	nts/sec .37" .78" ding on ce	

	maging system	
Camera type	360° Spherical camera, additional adjustable	
	external cameras as option	
Number of cameras	6 sensors	
CCD size	2048 x 2448, 3.45 μm pixel size	
Lens	4.4 mm	
Resolution	30 MP (5 MP x 6 sensors), 10 FPS	
	JPEG compressed	
Coverage	90% of full sphere	
High Dynamic	Cycle 4 gain and exposure presets	
Range (HDR)		
Positioning and orientation system		
GNSS system	Multiple GPS, GLONASS, Galileo, BeiDou,	
•	SBAS and QZSS constellation, L-Band, single	
	and dual antenna support	
IMU update rate	Standard 200 Hz (user selectable 1 to 1000 Hz)	
Gyro bias	≤0.1 deg/hr, 1σ (max)	
instability (25°C)	≤0.05 deg/hr, 1σ (typical)	
Gyro bias offset (25°C)	±2 deg/hr	
Gyro scale factor	≤200 ppm, 1σ	
Gyro range	±490 deg/sec	
Angle Random Walk	≤0.012 deg/√hr	
Accelerometer range	±10 g	
Accelerometer bias	<0.05 mg	
Accelerometer	250 ppm/°C, 1σ (max),	
scale factor	≤100 ppm/°C, 1σ (typical)	
Position accuracy	0.010 m RMS horizontal, 0.020 m RMS vertical,	
NO GNSS outage	0.005 degrees RMS pitch/roll, 0.017 degrees	
	RMS heading	
Wheel sensor (DMI)	Yes, optional	
Environmental		
Operating temperature	-10 °C to +40 °C	
Storage temperature	-20 °C to +50 °C	
IP rating	IP64	
Humidity (operating)	80%, non-condensing	
Maximum vehicle speed	110 km/h (68 mph)	
for data acquisition		
Humidity (operating)	80%, non-condensing	
Electrical		
Battery type	External battery in protected case, also	
	support direct vehicle power source	
Input voltage	24 V DC	
Power consumption	Typ. 240 W	
Operating time	Up to 8 hrs	
(1) Rounded values, selectable by measu (2) Typical values for average conditions. (3) Accuracy is the degree of conformity		

(4) Precision is the degree to which further measurements show the same results.

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^{*}Specifications are subject to change without notice.